

Special Issue

Advanced Control and Connection Techniques for Autonomous Vehicles

Message from the Guest Editor

A large part of the current research on autonomous vehicles concentrates on connectivity and motion planning. Although enormous efforts have been made to solve several theoretical and technological challenges in these two areas, several problems remain to be addressed. Many of these remaining issues require computationally intensive algorithms. A solution to this problem is offered by edge computing, which supports more resource capacity on mobile devices, and by highly parallel architecture systems, which are powerful and often underused. In this framework, the decomposition and parallelization of existing algorithms are extremely important tasks. For more information, please visit: mdpi.com/si/80210

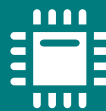
Guest Editor

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