

Special Issue

Advances in Tactile Sensing and Robotic Grasping

Message from the Guest Editor

Tactile perception, force feedback and intelligent grasping are the basics of intelligent robots. The development of tactile sensing devices and sensing technology is greatly promoting the ability of robots to be competent for various complex object recognition and grasping operations. However, compared with the human hand, there is still a huge gap between the existing tactile sensing and feedback control technologies. Therefore, the development of human-like tactile sensing devices, tactile recognition algorithms and tactile feedback control technology is the only way to improve robotic intelligence. This special issue focuses on novel tactile sensors, tactile perception, force feedback control and their applications in robotic grasping.

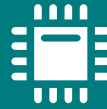
Guest Editor

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Deadline for manuscript submissions

closed (31 December 2022)



Sensors

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Impact Factor 3.5
CiteScore 8.2
Indexed in PubMed



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Sensors is a leading journal devoted to fast publication of the latest achievements of technological developments and scientific research in the huge area of physical, chemical and biochemical sensors, including remote sensing and sensor networks. Both experimental and theoretical papers are published, including all aspects of sensor design, technology, proof of concept and application. *Sensors* organizes Special Issues devoted to specific sensing areas and applications each year.

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