

Special Issue

Multi Sensor-Fusion for Autonomous Robots

Message from the Guest Editor

This Special Issue focuses on modern algorithms that perform fusing strategies with application for mobile robots. The techniques can range from direct and indirect fusion to centralized and decentralized methods. For this particular Special Issue, all results should illustrate the proposed algorithms operating on a physical robot. We look forward to receiving your contributions. Keywords

- mobile robotics
- sensor fusion
- field robotics
- SLAM
- robot localization
- autonomous vehicle navigation

Guest Editor

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Message from the Editor-in-Chief

Sensors is a leading journal devoted to fast publication of the latest achievements of technological developments and scientific research in the huge area of physical, chemical and biochemical sensors, including remote sensing and sensor networks. Both experimental and theoretical papers are published, including all aspects of sensor design, technology, proof of concept and application. Sensors organizes Special Issues devoted to specific sensing areas and applications each year.

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