

Special Issue

Intelligent Point Cloud Processing, Sensing and Understanding

Message from the Guest Editors

Point clouds are deemed to be one of the foundational pillars in representing the 3D digital world, despite irregular topologies among discrete points. Recently, the advancements in sensor technologies that acquire point cloud data for flexible and scalable geometric representation have paved the way for the development of new ideas, methodologies, and solutions in countless remote sensing applications. State-of-the-art sensors are capable of capturing and describing objects in a scene by using dense point clouds from various platforms (satellites, aerial, UAVs, vehicle-borne, backpacks, handheld, and static terrestrial), perspectives (nadir, oblique, and side view), spectra (multispectral), and granularity (point density and completeness). Meanwhile, the ever-expanding application areas of point cloud processing have already covered not only conventional domains in geospatial analysis, but also include manufacturing, civil engineering, construction, transportation, ecology, forestry, mechanical engineering, and so on. This Special Issue aims at contributions that focus on processing and utilizing point cloud data acquired from laser scanners and other 3D imaging systems.

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Sensors is a leading journal devoted to fast publication of the latest achievements of technological developments and scientific research in the huge area of physical, chemical and biochemical sensors, including remote sensing and sensor networks. Both experimental and theoretical papers are published, including all aspects of sensor design, technology, proof of concept and application. *Sensors* organizes Special Issues devoted to specific sensing areas and applications each year.

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