Special Issue

Advanced Approaches for Indoor Localization and Navigation

Message from the Guest Editor

Indoor localization has attracted enormous attention from both academia and industry, given the multitude of location-based services (LBS). Novel evolutions have been gaining increased attention, e.g., localization based on visible light signals, the availability of AoA and ToF data to enable hybrid RF approaches, 3D UAV indoor localization techniques, machine learning approaches, etc. It is expected that these ongoing research efforts will further support a widespread adoption of LBS, thanks to a higher accuracy and precision and a lower deployment cost.

This Special Issue aims to report high-quality research in recent advances in the indoor localization and navigation domain. Topics of interest include but are not limited to those covered by the keyword list below. Keywords

- RF-based localization
- Hybrid localization techniques (RSS, AoA, ToF, etc.)
- IMU-supported localization
- RFID localization
- Device-free indoor localization
- Magnetic indoor localization
- Machine learning techniques for indoor localization
- Visible light positioning (VLP)
- Novel indoor UAV and AGV navigation techniques

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Deadline for manuscript submissions

closed (30 April 2022)



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Sensors is a leading journal devoted to fast publication of the latest achievements of technological developments and scientific research in the huge area of physical, chemical and biochemical sensors, including remote sensing and sensor networks. Both experimental and theoretical papers are published, including all aspects of sensor design, technology, proof of concept and application. Sensors organizes Special Issues devoted to specific sensing areas and applications each year.

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