Special Issue

Recent Advances in Intelligent Vehicles and Intelligent Transportation Systems

Message from the Guest Editors

Intelligent vehicles are an integral part of intelligent transportation systems, which utilize a combination of sensors, cameras, radar, and advanced algorithms to navigate roads safely without human intervention. Ongoing research in this area focuses on several key areas, including environmental perception, decisionmaking, path planning, and vehicle control. Environmental Perception: Intelligent vehicles rely on a variety of sensors, such as lidars, radars, and cameras, to perceive their environment. These sensors provide data about the surrounding objects, including their position, speed, and direction. Research in this area aims to improve the accuracy and reliability of these sensors, as well as develop algorithms to fuse data from multiple sensors for a more comprehensive understanding of the vehicle's surroundings. This Special Issue addresses new environmental perception, decision-making, path planning, and vehicle control techniques used in intelligent vehicles and intelligent transportation systems. Survey papers are also welcome.

For more information, please visit: mdpi.com/si/R3029

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Deadline for manuscript submissions

15 February 2026



Sensors

an Open Access Journal by MDPI

Impact Factor 3.5 CiteScore 8.2 Indexed in PubMed



mdpi.com/si/204835

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Sensors is a leading journal devoted to fast publication of the latest achievements of technological developments and scientific research in the huge area of physical, chemical and biochemical sensors, including remote sensing and sensor networks. Both experimental and theoretical papers are published, including all aspects of sensor design, technology, proof of concept and application. Sensors organizes Special Issues devoted to specific sensing areas and applications each year.

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