

Special Issue

Integrated Navigation and Its Applications in Autonomous Agricultural Machinery

Message from the Guest Editors

This Special Issue focuses on Integrated Navigation and Its Applications in Autonomous Agricultural Machinery, aiming to highlight the latest advancements, methodologies, and applications in this domain. Central to these advancements is a multi-sensor fusion approach that harnesses the complementary strengths of GNSS (specifically RTK) for centimeter-level absolute positioning accuracy; MEMS-IMU for stable motion sensing in dynamic environments; visual navigation for rich environmental perception and feature matching; and radar for robust detection under adverse weather or lighting conditions. Thereby, this integrated solution effectively addresses critical challenges including continuous positioning error accumulation in unstructured terrains, instantaneous interference from dynamic obstacles, attitude solution drift during complex maneuvers, and localization failures in feature-deprived environments. We invite contributions exploring algorithm optimization (e.g., adaptive Kalman filtering, deep learning-based error correction), hardware-software co-design, and real-world validation in autonomous tractors, harvesters, and drones.

Guest Editors

Dr. Bingbo Cui

Dr. Yongyun Zhu

Dr. Zhen Ma

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Sensors
Editorial Office
MDPI, Grosspeteranlage 5
4052 Basel, Switzerland
Tel: +41 61 683 77 34
sensors@mdpi.com

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Message from the Editor-in-Chief

Sensors is a leading journal devoted to fast publication of the latest achievements of technological developments and scientific research in the huge area of physical, chemical and biochemical sensors, including remote sensing and sensor networks. Both experimental and theoretical papers are published, including all aspects of sensor design, technology, proof of concept and application. Sensors organizes Special Issues devoted to specific sensing areas and applications each year.

Editor-in-Chief

Prof. Dr. Vittorio M. N. Passaro

Dipartimento di Ingegneria Elettrica e dell'Informazione (Department of Electrical and Information Engineering), Politecnico di Bari, Via Edoardo Orabona n. 4, 70125 Bari, Italy

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