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Machine Learning and Artificial Intelligence for Better Perception, Estimation and Control Algorithms in Robotics

Guest Editors:

Prof. Dr. Hassen Fourati

Institute of Engineering, Univ.
Grenoble Alpes, CNRS, Inria,
Grenoble INP*, GIPSA-Lab, 38000
Grenoble, France

Prof. Dr. Hassen Seddik

Department of Electrical
Engineering, University of Tunis,
CEREP, ENSIT, Tunis, Tunisia

Deadline for manuscript
submissions:

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Message from the Guest Editors

Dear Colleagues,

During the last several years, a range of advanced algorithms in robotics have been developed, especially with the new generation of autonomous robots, which require a set of skills to carry out complex tasks autonomously. Perception, estimation and control algorithms are the fundamental capabilities with which these robots must be equipped in order to improve their navigation. Robots' tasks in real environments are not simple, and have been the focus of the scientific community's effort for decades, among these tasks are navigation and localization, environmental perception, path planning, moving between targets, real-time reactions to unexpected events, and people and object tracking.

Machine learning (ML) techniques present an opportunity to address the challenges facing the discipline through data-driven solutions. We are convinced that these techniques can better improve dedicated algorithms for perception, estimation and control. This Special Issue aims to publish novel works that apply machine learning and computational intelligence techniques for better perception, estimation and control algorithms in robotics.



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Special Issue



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Editor-in-Chief

Prof. Dr. Vittorio M. N. Passaro

Dipartimento di Ingegneria
Elettrica e dell'Informazione
(Department of Electrical and
Information Engineering),
Politecnico di Bari, Via Edoardo
Orabona n. 4, 70125 Bari, Italy

Message from the Editor-in-Chief

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Sensors Editorial Office
MDPI, Grosspeteranlage 5
4052 Basel, Switzerland

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