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Bioinspired Robotics

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Deadline for manuscript submissions: closed (11 January 2024)

Message from the Guest Editors

Dear colleagues,

Inspired by nature and biology, bioinspired robotics focuses on the novel design and control of robots. These robots include humanoid robots, crawling robots, jumping robots, modular robots, legged robots, flying robots, swimming robots, cobots, and climbing robots. Most of these robots have some locomotion system, and they often learn from nature. To contribute to this area extensive research has been conducted on biosensors, actuators, artificial muscles, biomaterials, bio-inspired control, artificial intelligence, adaptive learning, control using biological signals such as EMG and EEG, anthropomorphic design of robots, motion planning, vision-based control, autonomous navigation/control, and intelligent control. This Special Issue aims to gather cutting-edge research contributions in bioinspired robotics, focusing on the novel design and control of bioinspired robots in different application settings/environments, including home/clinical use, industry, search and rescue, underwater, space, and military applications.

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