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## Mobile Multi-Sensors in Positioning, Navigation, and Mapping Applications

Guest Editors:

**Dr. Sameh Nassar**

Mobile Multi-Sensor Systems  
Research Group, University of  
Calgary, Calgary, AB T2N 1N4,  
Canada

**Prof. Dr. Aboelmagd Noureldin**

Department of Electrical and  
Computer Engineering, Royal  
Military College of Canada  
(RMCC) with Cross-Appointment  
at both the School of Computing  
and the Department of Electrical  
and Computer Engineering,  
Queen's University, ON K7L 3N6,  
Canada

Deadline for manuscript  
submissions:

**closed (15 May 2021)**

### Message from the Guest Editors

The main objective of this Special Issue is to feature the current advances related to mobile multisensors in positioning, navigation, and mapping applications. Invited original research contributions can cover a wide range of topics, including but not limited to:

- Sensor calibration and evaluation
- Signal processing techniques
- Sensor data fusion
- Land, airborne, and marine applications
- Sensor stochastic error models
- Robotics
- Autonomous driving
- Optimal estimation techniques
- Autonomous underwater vehicles (AUV)
- Micro-electromechanical systems (MEMS)
- Indoor positioning and navigation
- Unmanned aerial vehicle (UAV) applications
- Multi-sensor systems in challenging environments
- Remote sensing applications
- Pipeline surveying and monitoring
- Vision-aided navigation



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# Special Issue



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### **Prof. Dr. Vittorio M. N. Passaro**

Dipartimento di Ingegneria  
Elettrica e dell'Informazione  
(Department of Electrical and  
Information Engineering),  
Politecnico di Bari, Via Edoardo  
Orabona n. 4, 70125 Bari, Italy

## Message from the Editor-in-Chief

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*Sensors* Editorial Office  
MDPI, Grosspeteranlage 5  
4052 Basel, Switzerland

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