Special Issue

Mechanics, Control, Design, Conceptualization and Fabrication of Soft Robotic Systems

Message from the Guest Editor

In parallel to recent developments in soft smart materials and additive manufacturing (also known as 3D printing), the field of soft robotics has been gathering significant momentum to bring a new dimension to the establishment of new robotic concepts, leading to the design and manufacture of soft robots, which will safely interact with (or operate within) the natural world better than their predecessors (*i.e.*, robots made of hard components). As a sub-class of biologically inspired engineering, it is a new paradigm to establish novel robotic systems primarily made of soft materials, components, and active monolithic structures containing embedded actuation, sensing, and motion/force transmission elements.

Guest Editor

Prof. Dr. Gursel Alici

School of Mechanical, Materials, Mechatronic and Biomedical Engineering, University of Wollongong, Wollongong, NSW 2522, Australia

Deadline for manuscript submissions

closed (31 January 2018)



Robotics

an Open Access Journal by MDPI

Impact Factor 3.3 CiteScore 7.7



mdpi.com/si/4724

Robotics
Editorial Office
MDPI, Grosspeteranlage 5
4052 Basel, Switzerland
Tel: +41 61 683 77 34
robotics@mdpi.com

mdpi.com/journal/robotics





Robotics

an Open Access Journal by MDPI

Impact Factor 3.3 CiteScore 7.7



About the Journal

Message from the Editor-in-Chief

It is my great pleasure to welcome you to our open access journal, *Robotics*, which is dedicated to both the foundations of artificial intelligence, bio-mechanics and mechatronics, and the real-world applications of robotic perception, cognition and actions. The 21st century is the robotics century and intelligent robots will change our lifestyle forever. Let us work together toward the realization of intelligent robots step by step. It is great fun to create intelligent robots and imagine their practical applications. *Robotics* is now ready to serve you in the long journey towards such a goal.

Editor-in-Chief

Prof. Dr. Marco Ceccarelli

LARM2: Laboratory of Robot Mechatronics, Department of Industrial Engineering, University of Rome Tor Vergata, Via del Politecnico 1, 00133 Roma, Italy

Author Benefits

Open Access:

free for readers, with article processing charges (APC) paid by authors or their institutions.

High Visibility:

indexed within Scopus, ESCI (Web of Science), dblp, Inspec, and other databases.

Journal Rank:

JCR - Q2 (Robotics) / CiteScore - Q1 (Control and Optimization)

