

# Special Issue

## Feature Papers 2020

### Message from the Guest Editor

This Special Issue will be a collection of "Feature Papers" discussing new knowledge or new cutting-edge developments in the science of robotics. We are looking for high-quality papers that contain either cutting-edge research results or comprehensive reviews. The accepted papers will be published free of charge in open access. Authors will be the Editorial Board Members and the researchers invited by the Editorial Office on behalf of Editor-in-Chief. Potential topics include but are not limited to the following items:

- Intelligent robotics, mechatronics and biomimetics;
- Novel and biologically inspired robotics;
- Modelling, identification and control of robotic systems;
- Biomedical, rehabilitation and surgical robotics;
- Exoskeletons, prosthetics and artificial organs;
- AI, neural networks and fuzzy logic in robotics;
- Multimodal human-machine interactions.

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### Guest Editor

Prof. Dr. Huosheng Hu

School of Computer Science and Electronic Engineering, University of Essex, Colchester CO4 3SQ, UK

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### Deadline for manuscript submissions

closed (15 December 2020)



## Robotics

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CiteScore 7.7



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## About the Journal

### Message from the Editor-in-Chief

It is my great pleasure to welcome you to our open access journal, *Robotics*, which is dedicated to both the foundations of artificial intelligence, bio-mechanics and mechatronics, and the real-world applications of robotic perception, cognition and actions. The 21st century is the robotics century and intelligent robots will change our lifestyle forever. Let us work together toward the realization of intelligent robots step by step. It is great fun to create intelligent robots and imagine their practical applications. *Robotics* is now ready to serve you in the long journey towards such a goal.

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### Editor-in-Chief

Prof. Dr. Marco Ceccarelli

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indexed within Scopus, ESCI (Web of Science), dblp, Inspec, and other databases.

#### Journal Rank:

JCR - Q2 (Robotics) / CiteScore - Q1 (Control and Optimization)