

## Special Issue

# Applications and New Trends in Metrology for Radar/LiDAR-Based Systems (Third Edition)

### Message from the Guest Editors

The scope of this Special Issue is to provide an overview of methods and instruments for, as well as practical experience with, testing LiDAR and radar systems and subsystems (land-based, shipborne, and onboard drones, aircraft, and satellites), as well as to obtain measurements of environmental features through remote sensing applications. Specifically, topics relevant to this Special Issue include instrument test equipment for verification and validation in the industry, at customer sites, or in the field of operation; automation and remote test equipment; virtual reality technologies; and both LiDAR and radar remote sensing applications. Other topics relevant to this Special Issue are the state-of-the-art radar system architectures and related digital and software technologies; cognitive radars and the analysis of human-in-the-loop aspects in radar systems; dual-function radar communications and radar systems; waveform design; radar detection theory and radar signal processing; theory, algorithms, and applications (RTAA); target classification; micromotion estimation.

### Guest Editors

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### Deadline for manuscript submissions

31 December 2025



## Remote Sensing

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### Message from the Editor-in-Chief

*Remote Sensing* is now a prominent international journal of repute in the world of remote sensing and spatial sciences, as a pioneer and pathfinder in open access format. It has highly accomplished global remote sensing scientists on the editorial board and a dedicated team of associate editors. The journal emphasizes quality and novelty and has a rigorous peer-review process. It is now one of the top remote sensing journals with a significant Impact Factor, and a goal to become the best journal in remote sensing in the coming years. I strongly recommend *Remote Sensing* for your best research publications for a fast dissemination of your research.

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### Editor-in-Chief

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