



Point Cloud Processing in Remote Sensing

Guest Editors:

Dr. Wei Yao

Dr. Francesco Pirotti

Dr. Naoto Yokoya

Dr. Yusheng Xu

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Message from the Guest Editors

Dear Colleagues,

Point clouds are deemed to be one of the foundational pillars in representing the 3D digital world despite irregular topology among discrete points. Recently, the advancement in sensor technologies that acquire point cloud data for a flexible and scalable geometric representation has paved the way for the development of new ideas, methodologies and solutions in countless remote sensing applications. The state-of-the-art sensors are capable of capturing and describing objects in a scene by using dense point clouds from various platforms (satellite, aerial, UAV, vehicle-borne, backpack, handheld and static terrestrial), perspectives (nadir, oblique and side-view), spectrums (multispectral), and granularity (point density and completeness). Meanwhile, the ever-expanding application areas of point cloud processing have already covered not only conventional domains in geospatial analysis, but also include manufacturing, civil engineering, construction, transportation, ecology, forestry, mechanical engineering and so on.

The Special Issue aims at contributions that focus on processing and utilizing point cloud data acquired from laser scanners





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Editors-in-Chief

Dr. Prasad S. Thenkabail

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Western Geographic Science
Center (WGSC), 2255, N. Gemini
Dr., Flagstaff, AZ 86001, USA

Prof. Dr. Dongdong Wang

Institute of Remote Sensing and
Geographic Information Systems,
Peking University, Beijing, China

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Remote Sensing Editorial Office
MDPI, Grosspeteranlage 5
4052 Basel, Switzerland

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