



Advances in Understanding and 3D Semantic Modeling of Large-Scale Urban Scenes from Point Clouds

Guest Editors:

Dr. Dong Chen

Dr. Zhengxin Zhang

Dr. Jiju Poovvancheri

Prof. Dr. Takis Mathiopoulos

Prof. Dr. Sisi Zlatanova

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Message from the Guest Editors

Dear Colleagues,

Driven by many applications and the improvement of 3D data acquisition technology, computer vision, and remote sensing communities are now focusing on deep learning-based and knowledge-based algorithms to tackle the challenges in understanding and 3D semantic modeling of large-scale urban scenes.

We position our Special Issue to support the ongoing efforts in 3D scanning and modeling industry and applications of LiDAR/RGB-D/photogrammetric point clouds. The topics of this Special Issue include, but are not limited to:

- Enhancement, registration, filtering of point clouds;
- Semantic, instance, panoptic, and part-level segmentation;
- Large-scale outdoor scene and indoor scene reconstruction;
- Detail synthesis and implicit modeling of urban scenes;
- 3D modeling of buildings, bridges, roads, trees, and utilities;
- Rendering and visualization of urban scenes;
- Polyhedral meshes, procedural models and model simplification;
- Innovative applications in smart cities, VR/AR, autonomous driving, indoor navigation, etc.





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Senior Scientist (ST), U. S.
Geological Survey (USGS), USGS
Western Geographic Science
Center (WGSC), 2255, N. Gemini
Dr., Flagstaff, AZ 86001, USA

Message from the Editor-in-Chief

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Remote Sensing Editorial Office
MDPI, Grosspeteranlage 5
4052 Basel, Switzerland

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