

Special Issue

Modern Trends in Computation and Control in Autonomous Robotics Systems

Message from the Guest Editor

As our society rapidly evolves into the robot era, autonomous robot technologies become one of the key technologies to enable the robots to seamlessly integrate into human society. This special issue aims to address the fundamental computation and control challenges faced by the rapidly evolving autonomous robotics systems and expects to have profound impacts on both the applications and the research of such systems. The primary goal of this special issue is to explore and disseminate the novel ideas and research in the diverse aspects of autonomous robotics systems.

- classic and emerging control theories and practices for the autonomous robotic systems
- computational methods for sensor data fusion and interpretation
- machine learning techniques for object detection and recognition
- Simultaneous Localization and Mapping (SLAM) algorithms and frameworks
- path planning algorithms and optimization techniques
- adaptive and learning-based navigation strategies
- AI-driven decision-making and planning in robotics
- computational approaches for ensuring safety in autonomous systems
- verification and validation of autonomous robotic algorithms

Guest Editor

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About the Journal

Message from the Editor-in-Chief

The journal *Mathematics* publishes high-quality, refereed papers that treat both pure and applied mathematics. The journal highlights articles devoted to the mathematical treatment of questions arising in physics, chemistry, biology, statistics, finance, computer science, engineering and sociology, particularly those that stress analytical/algebraic aspects and novel problems and their solutions. One of the missions of the journal is to serve mathematicians and scientists through the prompt publication of significant advances in any branch of science and technology, and to provide a forum for the discussion of new scientific developments.

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