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# **Mathematical Methods in Artificial Intelligence and Robotics**

Guest Editor:

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# **Message from the Guest Editor**

The purpose of this Special Issue is to disclose the latest progress and new methods on artificial intelligence and robotics, which provide intelligent processing of large volumes of fuzzy information in operational environments configured with embedded sensor networks and cloud services under conditions of uncertainty environmental variability. Original work in the field of technological foundations for the application of artificial intelligence and machine learning methods in the digital analysis of natural language and the management of interoperable socio-cyber-physical systems and robotic research is encouraged. The Special Issue examines mathematical models; algorithms and software; hardware control of ground, water, and underwater robots; and unmanned aerial vehicles and their built-in and attached equipment, including video cameras, sensors, repeaters, manipulators, grippers, and other actuators.











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