Special Issue

Intelligent Unmanned Aerial Vehicles Control, Navigation and Applications

Message from the Guest Editor

Unmanned Aerial Vehicles (UAVs) have become an indispensable technology in modern society, finding widespread applications in surveillance, logistics, environmental monitoring, agriculture, and disaster management. Intelligent control, navigation, and decision-making systems are the core technologies that enable UAVs to operate safely, autonomously, and efficiently in complex and dynamic environments. However, the diversity of flight conditions, mission objectives, and environmental constraints poses significant challenges to the design and implementation of such intelligent systems. Consequently, research on intelligent UAV control, navigation, and applications has gained increasing attention in recent years. This Special Issue aims to synthesize cutting-edge research and developments in the field of intelligent UAVs, addressing key challenges such as autonomous flight control, multi-sensor fusion for navigation, swarm coordination, and Al-based mission planning. Contributions focusing on theoretical advances, experimental validation, and emerging applications are highly encouraged.

Guest Editor

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Message from the Editor-in-Chief

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Our aim is to encourage scientists to publish their experimental and theoretical results in as much detail as possible. There is no restriction on the length of the papers. Full experimental and/or methodical details must be provided.

There are, in addition, unique features of this journal: Manuscripts regarding research proposals and research ideas will be particularly welcomed; Electronic files or software regarding the full details of the calculation and experimental procedure - if unable to be published in a normal way can be deposited as supplementary material.

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