Special Issue

Design and Application of Underwater Vehicles and Robots

Message from the Guest Editors

Autonomous underwater vehicles (AUVs) are a challenging issue of modern robotic science. AUVs are an extremely heterogeneous group of vehicles of various sizes that are able to operate in a submarine environment with a certain degree of autonomy. In some applications, an AUV is more often referred to as an unmanned undersea vehicle (UUV). Underwater gliders are a subclass of AUVs. This Special Issue will accept high-quality articles that contain original research results as well as review articles, and will allow readers to learn more about technologies related to the potentiality of AUVs, including, but not limited to, the following topics:

- Autonomous underwater vehicles;
- AUV design;
- AUV control;
- AUV guidance, navigation and path planning;
- AUV attitude estimation;
- Underwater target tracking;
- Vehicle modeling and simulation;
- Cooperative underwater vehicle manipulator systems;
- Intelligence and autonomy for underwater robotic vehicles;
- Underwater glider design and applications.

Guest Editors

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Deadline for manuscript submissions

30 November 2025

Machines

an Open Access Journal by MDPI

Impact Factor 2.5
CiteScore 4.7

mdpi.com/si/177226

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About the Journal

Message from the Editor-in-Chief

Machines is an international, peer reviewed journal on machinery and engineering. It publishes research articles, reviews and communications.
Our aim is to encourage scientists to publish their experimental and theoretical results in as much detail as possible. There is no restriction on the length of the papers. Full experimental and/or methodical details must be provided.
There are, in addition, unique features of this journal: Manuscripts regarding research proposals and research ideas will be particularly welcomed; Electronic files or software regarding the full details of the calculation and experimental procedure - if unable to be published in a normal way can be deposited as supplementary material.

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