

Special Issue

Design, Control and Application of Precision Robots

Message from the Guest Editor

Precision robots integrate mechanics, control theory and AI to achieve micro/nano accuracy in complex environments. Their advanced design combines high-rigidity structures with flexible mechanisms for monolithic integration, complemented by encoders and vision sensors to minimize positioning errors. Control algorithms—from classical PID to adaptive neural networks—enable real-time compensation for dynamic disturbances. Applications include semiconductor wafer handling, robotic surgery and satellite assembly, where precision and reliability are critical. Recent advancements feature hybrid learning control frameworks and digital twin integration for predictive maintenance. Driven by Industry 4.0 demands, these robots are evolving toward human–robot collaboration with enhanced force/torque sensing. The field continues to advance in multi-objective optimization, fault-tolerant control and energy-efficient actuation.

Guest Editor

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Message from the Editor-in-Chief

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