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Control of Robotic Systems

Guest Editors:

Dr. Jose De Jesus Rubio

Dr. Genaro Ochoa

Dr. Ricardo Balcazar

Dr. Luis Arturo Soriano

Deadline for manuscript submissions:

closed (30 June 2022)

Message from the Guest Editors

Original contributions are solicited on topics including but not limited to the following:

- Adaptive model-based or evolving control of robotic systems;
- Neural network or fuzzy control of robotic systems;
- Intelligent or backstepping control of robotic systems;
- Feedback or geometric control of robotic systems;
- Sliding mode or robust control of robotic systems;
- Structure at infinity or structure control of robotic systems;
- Observer-based or active-rejection control of robotic systems;
- Optimal or optimization control of robotic systems;
- Other alternative control methods for robotic systems.











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Editor-in-Chief

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Message from the Editor-in-Chief

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Our aim is to encourage scientists to publish their experimental and theoretical results in as much detail as possible. There is no restriction on the length of the papers. Full experimental and/or methodical details must be provided.

There are, in addition, unique features of this journal: Manuscripts regarding research proposals and research ideas will be particularly welcomed; Electronic files or software regarding the full details of the calculation and experimental procedure - if unable to be published in a normal way can be deposited as supplementary material.

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