

# Special Issue

## Localization in Wireless Sensor Networks

### Message from the Guest Editors

This Special Issue is focused on real-time target localization and tracking techniques in wireless sensor networks. Research articles, review articles as well as short communications are invited. **Topics of Interest** Suitable topics include, but are not limited to:

- Single target tracking
- Multiple target tracking
- Continuous target tracking
- Prediction-based target tracking
- Range estimation
- Range free localization
- Range based localization
- Acoustic localization
- Visible light localization
- Hybrid localization
- Collaborative localization and mapping
- Network localization
- Distributed localization
- Indoor localization
- Underwater localization
- Ad hoc or opportunistic localization
- Relay network localization
- Multi-static sonar localization and tracking
- Energy-efficient localization and tracking
- Novel applications of localization and tracking
- Survey of localization and tracking technologies

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### Guest Editors

Dr. Marko Beko

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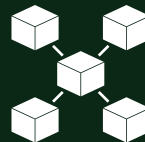
Prof. Slavisa Tomic

Department of Computer Engineering, Universidade Lusófona de Humanidades e Tecnologias, Portugal

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### Deadline for manuscript submissions

closed (31 October 2019)



## Journal of Sensor and Actuator Networks

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Impact Factor 4.2  
CiteScore 9.4



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## About the Journal

### Message from the Editor-in-Chief

I encourage you to contribute research and comprehensive review articles for publication in Journal of Sensors and Actuator Networks (JSAN), an international, open access journal which provides an advanced forum for research findings in areas of sensors and actuators. The journal publishes original research articles, reviews, conference proceedings (peer reviewed full articles) and communications. I am confident you will find the journal contributes to enhancing understanding of sensors and actuators and fostering applications of sensor-based measurements and effective actuator incorporation.

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### Editor-in-Chief

Prof. Dr. Lei Shu

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