

# Special Issue

## Deep Learning for Sensors and Actuators

### Message from the Guest Editor

The Special Issue titled “Deep Learning for Sensors and Actuators” aims to present current concrete work that successfully uses deep learning approaches in sensor data processing or actuator control. Possible contributions for this Special Issue could come from the following subject areas, for example:

- Deep learning for sensor data time series analysis
- Deep learning for heterogeneous sensor networks
- Deep learning for multimodal sensor data fusion
- Deep learning for the control of robots and other actuator systems
- Deep learning for the control of systems/machines
- Deep learning for embedded systems with sensors and actuators
- Surveys/overviews on the topic of “deep learning for sensor data processing”
- Surveys/overviews on the topic of “deep learning for the control of actuators”

This Special Issue is based on contributions to the Deep Learning Update (DLU) 2021 Conference (see <http://www.deep-learning-update.org/>). Authors of selected outstanding papers from the conference are invited to submit an extended version of their work. Furthermore, completely new submissions from the community are also welcome.

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### Guest Editor

Prof. Dr. Jürgen Brauer

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### Deadline for manuscript submissions

closed (15 August 2021)



## Journal of Sensor and Actuator Networks

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Impact Factor 3.3  
CiteScore 7.9



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## About the Journal

### Message from the Editor-in-Chief

I encourage you to contribute research and comprehensive review articles for publication in Journal of Sensors and Actuator Networks (JSAN), an international, open access journal which provides an advanced forum for research findings in areas of sensors and actuators. The journal publishes original research articles, reviews, conference proceedings (peer reviewed full articles) and communications. I am confident you will find the journal contributes to enhancing understanding of sensors and actuators and fostering applications of sensor-based measurements and effective actuator incorporation.

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### Editor-in-Chief

Prof. Dr. Lei Shu

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manuscripts are peer-reviewed and a first decision is provided to authors approximately 19 days after submission; acceptance to publication is undertaken in 5.6 days (median values for papers published in this journal in the second half of 2024).