



## Subsea Robotics

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Deadline for manuscript  
submissions:

**closed (25 September 2023)**

### Message from the Guest Editors

Dear Colleagues,

The demand for ocean exploration down to the deep seafloor (e.g., ocean resource exploration and ocean observations) has promoted innovations in underwater technology. As most underwater vehicles are unable to operate on the seafloor and even have difficulty reaching there at current stage, subsea robotics are urgently required to be deployed and operate on the seafloor. The purpose of this Special Issue is to publish the most exciting research with respect to the design, control, optimization and implementation of subsea robotics, to provide a rapid turn-around time regarding reviewing and publishing, and to disseminate the articles freely for research, teaching, and reference purposes.

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*Guest Editors*





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## Message from the Editor-in-Chief

*Journal of Marine Science and Engineering (JMSE, ISSN: 2077-1312)* focuses on research in the fields of Ocean Engineering, Coastal Engineering, Physical Oceanography, Geological Oceanography, Marine Biology, and Marine Environmental Science. It publishes reviews, regular research papers, and short communications, as well as Special Issues on particular subjects. Our aim is to encourage scientists to publish their experimental and theoretical results in as much detail as possible. There is no restriction on the maximum length of the papers.

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