

Special Issue

The Current State of Robotic Surgery in Urology

Message from the Guest Editor

I am pleased to present the Special Issue "The Current State of Robotic Surgery in Urology", with the aim of collecting clinical–surgical updates in the field of urological robotic surgery. Robotic surgery has effectively replaced open and laparoscopic surgery; all urological interventions can now be performed through the robotic approach, and for many indications, robotic surgery represents the gold-standard technique. In this Special Issue, in particular, the robotic experience will be shared in terms of consolidation of the technique, selection of patients, dedicated post-operative patient management protocols, implementation and improvement of old surgical indications, new clinical–surgical indications and new technologies applied to robotic surgery. In this way, the experience of different operational units can be shared, with the aim of defining the state of the art, updating the situation of "robotic" trends and with the aim of increasing the knowledge of all urologists. The following formats will be considered and accepted: original articles and reviews

Guest Editor

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Deadline for manuscript submissions

closed (25 March 2026)



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There has been an explosion of gene and target based research and therapeutics in the multitude of fields that compose clinical medicine. The *Journal of Clinical Medicine's* (JCM) staff and editorial board are dedicated to providing cutting edge, timely, and peer-reviewed articles covering the diverse subspecialties of clinical medicine. The journal publishes concise, innovative, and exciting research articles as well as clinically significant articles and reviews that are pertinent to the myriad of disciplines within medicine. The articles published are relevant to both primary care physicians and specialists. The journal's full-texts are archived in PubMed Central and indexed in PubMed. Please consider submitting your manuscripts for publication to our journal and check us out on-line!

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