

## Special Issue

# High Definition Maps for Intelligent Transportation Applications

### Message from the Guest Editors

Autonomous driving vehicles, or self-driving cars, have seen enormous progress in recent years. With advances in computing and sensor technologies, onboard systems can deal with a large amount of data and achieve real-time processes continuously and accurately. These systems also handle several specialized functional schemes such as positioning, mapping, perception, motion planning, and control. These key components are essential for the vehicle to achieve fully autonomous operation. In addition, high-definition (HD) maps provide detailed map information for navigating autonomous vehicles to ensure navigation safety to protect human lives. The map itself serves as an additional “pseudo sensor” of the car and significantly enhances the performance and accuracy of perception and positioning algorithms, which are necessary for the vehicle to drive autonomously. This Special Issue will cover relevant topics and trends in high-definition (HD) maps for intelligent transportation applications and also introduce the new tendencies of this new paradigm in geospatial science.

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### Guest Editors

Prof. Dr. Kai-Wei Chiang

Dr. Chenglu Wen

Dr. Mohamed Elhabiby

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### Deadline for manuscript submissions

closed (31 December 2022)



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*Geomatics*  
MDPI, Grosspeteranlage 5  
4052 Basel, Switzerland  
Tel: +41 61 683 77 34  
[geomatics@mdpi.com](mailto:geomatics@mdpi.com)

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### Message from the Editor-in-Chief

*Geomatics* is an information technology discipline which integrates the tasks of gathering, storing, processing, modeling, analyzing, and delivering spatially referenced or location information.

*Geomatics* journal offers a new forum to promote multidisciplinary research over broad ranges geomatics innovative research and applications. Original contributions in the form of research papers, communications, letters, short notes, and reviews on all aspects of *Geomatics* are invited.

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### Editor-in-Chief

Prof. Dr. Enrico Corrado Borgogno Mondino  
Department of Agricultural, Forest and Food Sciences, University of  
Turin, L.go Braccini 2, 10095 Grugliasco, Italy

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