# **Special Issue**

# Advanced Control Strategies for Enhanced Performance and Efficiency in Electric Autonomous Vehicles

## Message from the Guest Editor

Topics of interest for this Special Issue include, but are not limited to, the following:

- Optimized control methods for electric vehicles considering real-time control performance.
- Vehicle stability control under extreme conditions.
- Enhancement methods for motion control considering uncertainties.
- Environmental and vehicle state parameter estimation for motion control.
- Data-Driven advanced vehicle motion control methods, such as reinforcement learning, deep learning, etc.
- Motion control methods for electric vehicles considering energy efficiency optimization.
- System integration and optimization of motion control for electric vehicles.
- Active fault-tolerant control to ensure vehicle safety.
- Motion planning and control of vehicles in spatially constrained environments.
- Optimized control methods for electric vehicles in complex and constrained environments.
- Modeling and motion control of electric vehicles with special configurations, such as multi-axle vehicles and articulated vehicles.
- Optimized motion control methods for electric vehicles considering actuator or communication delays.
- Cooperative control strategies for connected electric vehicles.

### **Guest Editor**

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## Deadline for manuscript submissions

31 December 2025



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## Message from the Editor-in-Chief

Electronics is a multidisciplinary journal designed to appeal to a diverse audience of research scientists, practitioners, and developers in academia and industry. The journal is devoted to fast publication of latest technological breakthroughs, cutting-edge developments, and timely reviews of current and emerging technologies related to the broad field of electronics. Experimental and theoretical results are published as regular peer-reviewed articles or as articles within Special Issues guest-edited by leading experts in selected topics of interest.

### Editor-in-Chief

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