

Special Issue

Force and Tactile Sensing for Robots

Message from the Guest Editors

This Special Issue gives an opportunity to researchers from robotics as well as from the discipline of material and technology development to get an insight into the excellent work done in the respective fields. The topics of interest include, but are not limited to the following:

- Tactile Sensing Technologies
- Tactile Objects' Perception
- Tactile Objects' Interaction, Grasp, and Manipulation
- Tactile-based Human–Robot Interaction
- Tactile-Based Human–Robot Communication

Welcome to contribute.

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About the Journal

Message from the Editor-in-Chief

Electronics is a multidisciplinary journal designed to appeal to a diverse audience of research scientists, practitioners, and developers in academia and industry. The journal is devoted to fast publication of latest technological breakthroughs, cutting-edge developments, and timely reviews of current and emerging technologies related to the broad field of electronics. Experimental and theoretical results are published as regular peer-reviewed articles or as articles within Special Issues guest-edited by leading experts in selected topics of interest.

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