

Special Issue

Multi-UAV Systems and Mobile Robots

Message from the Guest Editors

Nowadays, it is difficult for single-configuration robots to complete efficient tasks in complex multimedia environments. The combination of unmanned aerial vehicle cluster systems and heterogeneous mobile robots such as ocean and land robots has become an important breakthrough in solving the above problems. The combination of multiple unmanned aerial vehicle systems and ocean and land mobile robots has a strong and scalable collaborative ability and a multi-medium and multi-task space. The implementation of the core functions of the aforementioned intelligent system involves key technologies such as high-performance electronic design, intelligent control, and multi-sensor and multi-information fusion of robot systems, which is closely related to the scope of this journal's submission. The topics include, but are not limited to the following:

- Advanced modeling and identification of complex robotic systems;
- Ocean/land/air robot system control based on trajectory planning/optimization;
- Mobile robot system control based on intelligent learning;
- Human-robot collaborative control of heterogeneous robot cluster system;

Guest Editors

Dr. Daxiong Ji

Ocean College, Zhejiang University, Hangzhou, China

Dr. Xu Yang

Institute of Automation, Chinese Academy of Sciences, Beijing 100000, China

Dr. Chenglong Du

School of Automation, Central South University, Changsha 410083, China

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Editorial Office
MDPI, Grosspeteranlage 5
4052 Basel, Switzerland
Tel: +41 61 683 77 34
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Electronics is a multidisciplinary journal designed to appeal to a diverse audience of research scientists, practitioners, and developers in academia and industry. The journal is devoted to fast publication of latest technological breakthroughs, cutting-edge developments, and timely reviews of current and emerging technologies related to the broad field of electronics. Experimental and theoretical results are published as regular peer-reviewed articles or as articles within Special Issues guestedited by leading experts in selected topics of interest.

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Prof. Dr. Flavio Canavero

Department of Electronics and Telecommunications, Politecnico di Torino, 10129 Torino, Italy

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