Special Issue

Path Planning and Control for Robotics

Message from the Guest Editors

To promote the innovation in robot path planning and control methodologies, this special issue is to solicit but not limit the following topics:

- Object recognition to promote cognitive robotics in path planning
- Human motion synthesis to develop the bionic robot
- Wireless sensor and actuator network used in path planning and control of robots
- Path planning for automation of surgery robot
- Nonholonomic system to mobile robotics
- Collision detection and path-planning in structured or unstructured environments
- Computational structure to support path planning and control
- Trajectory tracking and path planning
- Collaborative robot and robot motion-control
- Controllability of mobile robots for path planning
- Steering methods and topological optimization
- Supervised and unsupervised learning for environment survey and path planning

The deadline to submit papers to this special issue is 30 November 2022. However, papers submitted in advance will be peer-reviewed and may be published well before this deadline. For moe details, please click here.

Guest Editors

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Deadline for manuscript submissions

closed (15 July 2023)



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About the Journal

Message from the Editor-in-Chief

Electronics is a multidisciplinary journal designed to appeal to a diverse audience of research scientists, practitioners, and developers in academia and industry. The journal is devoted to fast publication of latest technological breakthroughs, cutting-edge developments, and timely reviews of current and emerging technologies related to the broad field of electronics. Experimental and theoretical results are published as regular peer-reviewed articles or as articles within Special Issues guest-edited by leading experts in selected topics of interest.

Editor-in-Chief

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manuscripts are peer-reviewed and a first decision is provided to authors approximately 16.8 days after submission; acceptance to publication is undertaken in 2.4 days (median values for papers published in this journal in the first half of 2025).

