

Special Issue

Recent Advances in Modelling, Control and Navigation of Ground and Aerial Robots

Message from the Guest Editors

Papers presenting different approaches from nonlinear control theory applied to trajectory tracking control and navigation of robots, as well as various robot control systems, are welcome.

- robotics, robot manipulators
- mobile robots
- mobile manipulators
- unmanned aerial vehicles
- collective robotics
- robot control and navigation
- backstepping control
- sliding mode control
- computed torque control
- Lyapunov-based nonlinear feedback control
- intelligent control

I/We look forward to receiving your contributions.

Guest Editors

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About the Journal

Message from the Editor-in-Chief

Electronics is a multidisciplinary journal designed to appeal to a diverse audience of research scientists, practitioners, and developers in academia and industry. The journal is devoted to fast publication of latest technological breakthroughs, cutting-edge developments, and timely reviews of current and emerging technologies related to the broad field of electronics. Experimental and theoretical results are published as regular peer-reviewed articles or as articles within Special Issues guest-edited by leading experts in selected topics of interest.

Editor-in-Chief

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