

Special Issue

Human Robot Interaction and Intelligent System Design

Message from the Guest Editors

Humans and robots are expected to work together closely, interactively and collaboratively, sharing working spaces, in a large number of task scenarios. First, intelligent systems need to be designed with the integration of novel and multiple sensors to capture different types of sensing information (such as image, sound, bio-signal, force, tactile) in the working environments. Correspondingly, advanced signal processing and fusion techniques are required to extract important features from multimodal data. With these as inputs, intelligent learning (e.g., imitation learning, deep learning and reinforcement learning), control (such as adaptive control, bio-inspired control) and optimization (such as black box and model-based techniques) algorithms are then needed to improve the robot manipulation abilities and to improve human-robot interaction performances. The goal of the Special Issue “Human Robot Interaction and Intelligent System Design” is to cover recent advancements in system design, advanced sensing, learning, control and optimization for human-robot interaction, as well as its novel applications.

Guest Editors

Prof. Dr. Chenguang Yang
Dr. Chao Zeng
Dr. Yanan Li

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Electronics
Editorial Office
MDPI, Grosspeteranlage 5
4052 Basel, Switzerland
Tel: +41 61 683 77 34
electronics@mdpi.com

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Message from the Editor-in-Chief

Electronics is a multidisciplinary journal designed to appeal to a diverse audience of research scientists, practitioners, and developers in academia and industry. The journal is devoted to fast publication of latest technological breakthroughs, cutting-edge developments, and timely reviews of current and emerging technologies related to the broad field of electronics. Experimental and theoretical results are published as regular peer-reviewed articles or as articles within Special Issues guestedited by leading experts in selected topics of interest.

Editor-in-Chief

Prof. Dr. Flavio Canavero

Department of Electronics and Telecommunications, Politecnico di Torino, 10129 Torino, Italy

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