# Special Issue

# Path Planning and Navigation for Autonomous Vehicles and Intelligent Robots

### Message from the Guest Editors

We are seeking innovative research contributions on topics such as path planning, perception, control, and autonomous navigation. We welcome reviews and original research articles focused on but not limited to the following topics:

- Path planning and trajectory generation;
- Robust techniques of motion control and motion planning;
- Perception, reasoning, communication, adaptation, and learning;
- Self-localization, mapping, navigation, and simultaneous localization and mapping;
- Autonomous navigation in real environments and complex scenarios;
- Autonomy, intelligent behaviors, and evolutionary and bio-inspired robots;
- Deep learning and reinforcement learning for autonomous vehicles:
- Multirobot and multi-agent systems, cooperation, and collaboration;
- Optimization and optimal control for autonomous vehicles;
- Industrial and agricultural applications of intelligent robots.

### **Guest Editors**

Prof. Dr. Ulises Orozco-Rosas

School of Engineering, CETYS Universidad, Tijuana 22210, BC, Mexico

Prof. Dr. Oscar Montiel Ross

Centro de Investigación y Desarrollo de Tecnología Digital, Instituto Politécnico Nacional, Mexico City 07738, Mexico

### Deadline for manuscript submissions

15 August 2026



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Electronics
Editorial Office
MDPI, Grosspeteranlage 5
4052 Basel, Switzerland
Tel: +41 61 683 77 34
electronics@mdpi.com

mdpi.com/journal/electronics





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### **About the Journal**

### Message from the Editor-in-Chief

Electronics is a multidisciplinary journal designed to appeal to a diverse audience of research scientists, practitioners, and developers in academia and industry. The journal is devoted to fast publication of latest technological breakthroughs, cutting-edge developments, and timely reviews of current and emerging technologies related to the broad field of electronics. Experimental and theoretical results are published as regular peer-reviewed articles or as articles within Special Issues guestedited by leading experts in selected topics of interest.

### Editor-in-Chief

Prof. Dr. Flavio Canavero

Department of Electronics and Telecommunications, Politecnico di Torino, 10129 Torino, Italy

### **Author Benefits**

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### **Rapid Publication:**

manuscripts are peer-reviewed and a first decision is provided to authors approximately 16.8 days after submission; acceptance to publication is undertaken in 2.4 days (median values for papers published in this journal in the first half of 2025).

