

## Special Issue

# Advances in Kinematic Planning and Dynamic Control of Intelligent Robots

### Message from the Guest Editors

The field of robotics is undergoing a paradigm shift driven by advancements in computational algorithms, sensor technologies, and adaptive control systems. Kinematic planning and dynamic control lie at the heart of enabling robots to perform complex tasks in unstructured environments, from industrial automation and autonomous navigation to medical robotics and human–robot collaborations. Research areas include, but are not limited to, the following

- Kinematic path planning for multi-joint and mobile robots.
- Dynamic modeling and control of robotic manipulators and legged systems.
- Real-time trajectory optimization under environmental constraints.
- Machine learning-driven motion planning for adaptive robotics.
- Collision avoidance in dynamic or cluttered environments.
- Human–robot interaction with emphasis on safety and compliance.
- Sensor fusion for enhanced localization and control accuracy.
- Energy-efficient actuation and torque optimization.
- Multi-robot coordination and swarm dynamics.
- Simulation frameworks for validating kinematic and dynamic models.

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### Guest Editors

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### Deadline for manuscript submissions

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## Electronics

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### Editor-in-Chief

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