

## Special Issue

# Parallel, Distributed, Edge Computing in UAV Communication

### Message from the Guest Editors

The UAV network is an important part of the sixth generation (6G) wireless communication system in the future. Compared with the traditional communication network based on ground infrastructure, the drone network has many unique attributes, such as low-cost, high mobility, easily deployment, widely coverage, strong viewing links, controllable mobility, etc., these features integrate communication, perception, computing, intelligence, and security. It provides new opportunities in enhancing coverage, improving spectrum efficiency, and user service quality. The UAV network is expected to provide communication, perception, computing, cache and other services for various application scenarios. However, the high mobility of drones has also brought great challenges to many aspects of the drone network application, including the intelligent network, channel modeling, flight deployment, mobility control, trajectory optimization, and optimization of drone networks, this has also become a bottleneck restricting such drone network development.

### Guest Editors

Dr. Yuan Gao

Beijing National Research Center for Information Science and Technology (BNRist), Tsinghua University, Beijing 100084, China

Prof. Dr. Su Hu

National Key Laboratory of Science and Technology on Communications, University of Electronic Science and Technology of China, Chengdu 611731, China

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Editorial Office  
MDPI, Grosspeteranlage 5  
4052 Basel, Switzerland  
Tel: +41 61 683 77 34  
[electronics@mdpi.com](mailto:electronics@mdpi.com)

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### Editor-in-Chief

Prof. Dr. Flavio Canavero

Department of Electronics and Telecommunications, Politecnico di  
Torino, 10129 Torino, Italy

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