Special Issue

Fault-Tolerant Strategies for Intelligent Soft Robotic Systems: Design and Control Perspectives

Message from the Guest Editors

Faults are inevitable in advanced engineering systems. In soft robotics, such risks are amplified by flexible materials and intricate actuation mechanisms, which can render traditional control schemes insufficient when dealing with faults. Consequently, the early integration of fault-tolerant strategies into soft robotic design and control is essential to maintain resilience, reliability, and operational continuity. This Special Issue aims to collect and disseminate the latest research on the design, analysis, and implementation of fault-tolerant strategies in soft robotic systems, with a strong emphasis on aerospace applications and the integration of Al-driven methods for both design and control. Research areas may include (but are not limited to) the following: Aldriven fault detection and fault-tolerant control for soft robots:

Integration of soft robotic systems with aerospace platforms;

Design, fabrication, and advanced materials for faultresilient soft robotic actuators, especially in aerospace environments;

Modeling, simulation, and real-time validation frameworks tailored to aerospace conditions; And so on.

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