

## Special Issue

# Fault-Tolerant Strategies for Intelligent Soft Robotic Systems: Design and Control Perspectives

### Message from the Guest Editors

Faults are inevitable in advanced engineering systems. In soft robotics, such risks are amplified by flexible materials and intricate actuation mechanisms, which can render traditional control schemes insufficient when dealing with faults. Consequently, the early integration of fault-tolerant strategies into soft robotic design and control is essential to maintain resilience, reliability, and operational continuity. This Special Issue aims to collect and disseminate the latest research on the design, analysis, and implementation of fault-tolerant strategies in soft robotic systems, with a strong emphasis on aerospace applications and the integration of AI-driven methods for both design and control. Research areas may include (but are not limited to) the following: AI-driven fault detection and fault-tolerant control for soft robots; Integration of soft robotic systems with aerospace platforms; Design, fabrication, and advanced materials for fault-resilient soft robotic actuators, especially in aerospace environments; Modeling, simulation, and real-time validation frameworks tailored to aerospace conditions; And so on.

### Guest Editors

Dr. Mahya Ramezani

Centre for Security, Reliability, and Trust (SNT), University of Luxembourg, L-1359 Luxembourg, Luxembourg

Prof. Dr. Holger Voos

Centre for Security, Reliability, and Trust (SNT), University of Luxembourg, L-1359 Luxembourg, Luxembourg

### Deadline for manuscript submissions

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Editorial Office  
MDPI, Grosspeteranlage 5  
4052 Basel, Switzerland  
Tel: +41 61 683 77 34  
[electronics@mdpi.com](mailto:electronics@mdpi.com)

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### Editor-in-Chief

Prof. Dr. Flavio Canavero

Department of Electronics and Telecommunications, Politecnico di  
Torino, 10129 Torino, Italy

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