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Physical Human-Robot Interaction and Robot Manipulation

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Deadline for manuscript submissions:

closed (31 August 2023)

Message from the Guest Editors

While robotics scientists are moving toward the creation of humanoid robots thought to be able to work alongside humans in human-centric and unstructured environments, industries are faced with even more complex tasks that require important technological advances and, in particular, human-like features in the new generation of robotic systems

This Special Issue collects the experience of academic and industrial scientists in order to discuss and present state-of-the-art technologies used to confront the most relevant problems in human–robot interaction application and autonomous object grasping and manipulation.

Potential submission topics include but are not limited to the following:

- Tactile/Force Sensor Technology;
- Vision Sensory Systems;
- Object Recognition;
- Object Grasping and Manipulation;
- Human-Robot Cooperative Systems;
- Human-Robot Interaction Control Algorithm;
- Trajectory Planner Algorithm for Grasping and Unintended Collision Avoidance.











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Message from the Editor-in-Chief

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