



Recent Advances in Motion Planning and Control of Autonomous Vehicles

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submissions:
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Message from the Guest Editors

There has been rapid progress made in the applications of autonomous vehicles on a structured urban road or in an unstructured indoor scenario. The purpose of this Special Issue is to present the most recent advances in the planning or control methodologies used for an autonomous vehicle.

Topics of interest include but are not limited to:

- Path/trajectory/motion planning and replanning;
- Path/trajectory/motion control;
- On-road/off-road planning and control;
- Modeling and simulation method for planning and/or control;
- Testing and validation method related to planning and/or control;
- Safety-related issues with planning and control;
- Security-related issues with planning and control;
- Human-machine interaction related to planning and/or control;
- Intelligent techniques/methods to planning and/or control;
- Integration of planning and control;
- Reviews of planning or control methodologies;
- Data-driven/model-based planning or control;
- Comparisons among different types of planning or control methods;
- Fault-tolerant planning and control;
- Cooperative planning and control;
- Real-world applications of planning and control.





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Message from the Editor-in-Chief

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