



Autonomous Navigation of Unmanned Maritime Vehicles

Guest Editors:

Dr. Dongdong Mu

College of Marine Electrical
Engineering, Dalian Maritime
University, Dalian 116026, China

Dr. Xiaojie Sun

College of Information
Engineering, Henan University of
Science and Technology,
Luoyang 471023, China

Dr. Cunhe Li

School of Electrical and
Electronic Engineering,
Shandong University of
Technology, Zibo 256600, China

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Message from the Guest Editors

Dear Colleagues,

This Special Issue aims to address issues involved in the analysis, design, and implementation of Autonomous Navigation of Unmanned Maritime Vehicles. This includes:

1. Intelligent agents and multi-agent systems;
2. Intelligent control of ships and ocean vehicles;
3. Intelligent perception and autonomous control of unmanned systems;
4. Multi-agent systems and intelligent transportation network control;
5. Intelligent control and detection technology;
6. Autonomous navigation control of surface or underwater vehicles;
7. Nonlinear control;
8. Unmanned systems;
9. Autonomous control of robots;
10. Information collection of ships or unmanned craft;
11. Ship or unmanned craft control technology;
12. Image processing techniques;
13. Field verification of unmanned systems;
14. Development trend of unmanned systems in the future.





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Editor-in-Chief

Prof. Dr. Flavio Canavero

Department of Electronics and
Telecommunications,
Politecnico di Torino, 10129
Torino, Italy

Message from the Editor-in-Chief

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Electronics Editorial Office
MDPI, Grosspeteranlage 5
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