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Recent Advances in Modelling, Control and Navigation of Ground and Aerial Robots

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Deadline for manuscript submissions: **31 July 2024**

Message from the Guest Editors

Papers presenting different approaches from nonlinear control theory applied to trajectory tracking control and navigation of robots, as well as various robot control systems, are welcome.

- robotics, robot manipulators
- mobile robots
- mobile manipulators
- unmanned aerial vehicles
- collective robotics
- robot control and navigation
- backstepping control
- sliding mode control
- computed torque control
- Lyapunov-based nonlinear feedback control
- intelligent control

I/We look forward to receiving your contributions.









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Message from the Editor-in-Chief

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