Message from the Guest Editors

In the foreseeable future the usage of a single robot will become obsolete, as there is an ever-increasing interest of multi-robot systems. This is due to the extended capabilities that the teams can offer, compared to the use of a single robot for the same task.

This special issue will focus in all aspects related to multi-robot teams including but not limited to:

- Theoretical foundations in multi-robot systems
- Multi-robot systems coordination and interaction
- Distributed control and planning
- Mapping, localization, and navigation in multi-robot systems
- Swarm robotics
- Novel sensors and actuators for multi-robot systems
- Real-world applications of multi-robot systems
- Machine learning in multi-robot systems
- IoT and Multi-Robot systems
- Multi-Robot systems in Education and Special Education

Welcome to contribute.