



Modelling, Control and Emerging Application for Unmanned Vehicles

Guest Editors:

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Deadline for manuscript
submissions:

closed (28 February 2023)

Message from the Guest Editors

Unmanned vehicles are critical in many fields, further attention should be paid to research identifying the requirements of unmanned vehicles, and the technologies necessary for the delivery of those requirements. The aim of this Special Issue is to bring together relevant research and researchers to address these important issues. This Special Issue seeks to consolidate past research and chart future research directions.

The topics of interests include, but are not limited to:

- Applications and requirements for unmanned vehicles;
- Receiver/sensor/antenna design technologies;
- Unmanned-vehicle-assisted 5G/6G-and-beyond communications;
- Multisource cooperative positioning methods in complex environments;
- Measurements/observables processing models (including error mitigation);
- System/sensor/spatial data integration or data fusion, and applications, with a particular focus on very high performance as measured in terms of the required navigation performance parameters of accuracy, integrity, continuity, and availability;
- Errors and their modelling;
- Interference (jamming, meaconing, and spoofing) and integrity/quality monitoring;
- Path planning and optimizing strategies.





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Editor-in-Chief

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Message from the Editor-in-Chief

Electronics is a multidisciplinary journal designed to appeal to a diverse audience of research scientists, practitioners, and developers in academia and industry. The journal is devoted to fast publication of latest technological breakthroughs, cutting-edge developments, and timely reviews of current and emerging technologies related to the broad field of electronics. Experimental and theoretical results are published as regular peer-reviewed articles or as articles within Special Issues guest-edited by leading experts in selected topics of interest.

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