Special Issue

Control, Planning, and Embodied Intelligence of Agile UAVs in Indoor Environments

Message from the Guest Editors

This Special Issue focuses on advancements in autonomous flight of unmanned aerial vehicles (UAVs) in complex indoor environments, which present unique challenges like GPS-denied conditions and dynamic obstacles. Effective navigation requires highperformance control systems, agile motion planning, and integrated perception and decision-making capabilities. We invite contributions addressing challenges such as precise state estimation, real-time obstacle avoidance, robust control under disturbances, and adaptation to cluttered environments. Topics of interest include agile flight control, perception-aware motion planning, vision-based navigation, learningbased control policies, and the design of lightweight UAV platforms. We look forward to original research articles and reviews that enhance this exciting field.

Guest Editors

Dr. Minghao Han

Dr. Bo Cai

Dr. Lin Zhao

Deadline for manuscript submissions

30 December 2025



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About the Journal

Message from the Editor-in-Chief

Drones is the only international open-access journal about the science, policy and technology of drones and its applications. Nowadays, the proliferation of drones is a reality for local policy makers, regulatory bodies, mapping authorities, startups and consolidated companies. There are many uses and benefits of drones: from the emergence of new sensors and the evolution of new platforms; to the development of specific software and the emergence of new applications. Drones publishes reviews, regular research papers, communications and short notes, without restriction on the length of papers. Drones seeks to provide a central forum for scholars engaged in drones' research and applications.

There is a need for high quality papers in this area and the *Drones* Editorial Board are widely recognized international leaders. *Drones* journal guarantees a serious peer review and a rapid publication across the whole discipline of drones.

Editor-in-Chief

Prof. Dr. Diego González-Aguilera

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