



## Biologically Inspired Assistive and Rehabilitation Robotics

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### Message from the Guest Editor

Wearable robots are robotic systems that can augment, support, and restore various physical abilities of the wearer. Different types of wearable robots have been proposed. Specifically, given their primary purpose of assisting people's physical abilities, wearable robots are often developed by imitating the principles of the human musculoskeletal system.

This Special Issue aims to introduce and share the latest research in the field of biologically inspired wearable robots. In particular, this Issue introduces various types of wearable robots that utilize biomimetics in multiple aspects, such as robot design, control algorithms, sensors, and recognition. This Issue also covers the utilization and evaluation of biologically inspired wearable robots.

