

Special Issue

State Estimation, Control, and Motion Planning of Unmanned Aircraft Systems (UASs)

Message from the Guest Editors

Unmanned aircraft systems are developing rapidly. Several control algorithms are being tested for use on-board UASs. Additionally, the use of data fusion and virtual sensor algorithms offers several new possibilities. Another important topic is autonomous navigation and autonomous flight plan change. This Special Issue of *Applied Sciences* on “State Estimation, Control and Motion Planning of Unmanned Aircraft Systems (UASs)” focuses on the broad topic of UAV state estimation, control algorithms and motion planning. Theoretical and empirical articles related to unmanned flying systems (all configurations, including but not limited to fixed-wing aircraft and rotorcraft) are welcome. **Keywords:** UAS control algorithms; measurement systems; data estimation; virtual sensors; data fusion; autonomous navigation; artificial intelligence in UAS

Guest Editors

Dr. Grzegorz Kopecki

Prof. Dr. Zbigniew Koruba

Prof. Dr. Izabela Krzysztofik

Dr. Jacek Pieniążek

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Applied Sciences
Editorial Office
MDPI, Grosspeteranlage 5
4052 Basel, Switzerland
Tel: +41 61 683 77 34
applsci@mdpi.com

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Message from the Editor-in-Chief

As the world of science becomes ever more specialized, researchers may lose themselves in the deep forest of the ever increasing number of subfields being created. This open access journal *Applied Sciences* has been started to link these subfields, so researchers can cut through the forest and see the surrounding, or quite distant fields and subfields to help develop his/her own research even further with the aid of this multi-dimensional network.

Editor-in-Chief

Prof. Dr. Giulio Nicola Cerullo
Dipartimento di Fisica, Politecnico di Milano, Piazza L. da Vinci 32,
20133 Milano, Italy

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