

## Special Issue

# Advanced Control and Sensing Technologies for Intelligent Underwater Systems

### Message from the Guest Editors

With the rapid advancement of intelligent underwater unmanned systems, achieving high autonomy, robustness, and adaptability in unstructured marine environments has become critical. Advanced control and perception technologies are central to enabling real-time sensing, intelligent decision-making, and autonomous operation. This Special Issue highlights cutting-edge research in control and perception for underwater systems, including:

- Sensor fusion and multi-modal perception
- Distributed/swarm control and autonomous navigation
- Model predictive control (MPC) and learning-based adaptive control
- Real-time signal processing and bionic perception methods
- New propulsion systems and motion planning

These technologies enhance underwater navigation, inspection, manipulation, and environmental interaction in complex conditions. We invite original research on theoretical advances, algorithms, simulations, and experimental validations, particularly studies involving field tests or sea trials. This issue aims to foster cross-disciplinary collaboration in control theory, robotics, AI, and ocean engineering, driving innovation in next-generation autonomous underwater systems.

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### Guest Editors

Dr. Yang Luo

Prof. Dr. Yong Cao

Prof. Dr. Feihu Zhang

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### Deadline for manuscript submissions

20 February 2026



## Applied Sciences

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## About the Journal

### Message from the Editor-in-Chief

As the world of science becomes ever more specialized, researchers may lose themselves in the deep forest of the ever increasing number of subfields being created. This open access journal *Applied Sciences* has been started to link these subfields, so researchers can cut through the forest and see the surrounding, or quite distant fields and subfields to help develop his/her own research even further with the aid of this multi-dimensional network.

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### Editor-in-Chief

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