Special Issue

Innovative Technologies in Image Processing for Robot Vision

Message from the Guest Editors

Robot vision is one of the primary approaches for robots to sense the environment. It has been widely used in various kinds of robots, including industrial robots, service robots, and specialized robots. Image processing is the fundamental technique of robot vision. Therefore, this Special Issue is intended for the presentation of new ideas and experimental results of image processing techniques in the application of robot vision. Research work of robot vision based on RGB images, RGBD images, the point could data, x-ray images, infrared images, etc. are all topics of interest. The subtasks of robot vision include, but are not limited to, visual object detection, visual object tracking, image face recognition, facial expression recognition, human posture detection, hand gesture recognition, visionbased navigation, vision measurement, product defect detection, etc. This Special Issue will publish highquality, original research papers, in the overlapping fields of: Image processing; Machine vision; Robot vision; Deep learning; Machine learning; Product defect detection.

Guest Editors

Dr. Deng Chen

Hubei Province Key Laboratory of Intelligent Robot, Wuhan Institute of Technology, Wuhan 430079, China

Dr. Hong Zheng

School of Electronic Information Engineering, Wuhan University, Wuhan, China

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Applied Sciences
Editorial Office
MDPI, Grosspeteranlage 5
4052 Basel, Switzerland
Tel: +41 61 683 77 34
applisci@mdpi.com

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As the world of science becomes ever more specialized, researchers may lose themselves in the deep forest of the ever increasing number of subfields being created. This open access journal Applied Sciences has been started to link these subfields, so researchers can cut through the forest and see the surrounding, or quite distant fields and subfields to help develop his/her own research even further with the aid of this multidimensional network.

Editor-in-Chief

Prof. Dr. Giulio Nicola Cerullo

Dipartimento di Fisica, Politecnico di Milano, Piazza L. da Vinci 32, 20133 Milano, Italy

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