

Topical Collection

Advances of Agricultural Robotics in Sustainable Agriculture 4.0

Message from the Collection Editors

The main aims of this focused section in *Agronomy* are to present the current state of the art in intelligent perception, behavior decision, path planning, flexible actuators for agricultural field robotics and to illustrate new results in several emerging research areas.

Submissions can present theoretical and experimental aspects in these areas. The topics of interest within the scope of this focused section include, but are not limited to:

- Advanced autonomy for unmanned mechatronics systems;
- Advanced machines or robotics for precision agriculture;
- The advancement of cooperative mechatronics systems for precision agriculture;
- Soft-grasping/soft-robotics manipulators;
- Harvesting robots.

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Message from the Editor-in-Chief

Agronomy draws together researchers from diverse areas of agricultural research with a common aim of enhancing agricultural productivity globally. The journal provides unlimited free access to all those interested in advancing agricultural science from both the research and general community. Papers are released immediately after acceptance through the internet.

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Editor-in-Chief

Prof. Dr. Leslie A. Weston

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