

Special Issue

Swarm Robotics for Agricultural Applications

Message from the Guest Editor

The focus of this Special Issue of *AgriEngineering* is the application of swarm robotics to agriculture. We seek studies with experimental results involving agricultural robots designed to operate autonomously, in parallel, and scalably. Sensors, software, end-effectors, and other payloads particularly suited for use with such robots will also be considered. By collecting several recent developments between covers, this issue seeks to achieve the critical mass needed to inspire a revolution in *practical* agricultural swarm robotics. For further reading, please visit the [Special Issue website](#).

Guest Editor

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Deadline for manuscript submissions

closed (1 November 2021)



AgriEngineering

an Open Access Journal
by MDPI

Impact Factor 3.0
CiteScore 4.7



mdpi.com/si/62244

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Retired Scientist from Agricultural Research Service, United States
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JCR - Q2 (Agricultural Engineering) / CiteScore - Q1 (Horticulture)

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manuscripts are peer-reviewed and a first decision is provided to authors approximately 20.6 days after submission; acceptance to publication is undertaken in 5.4 days (median values for papers published in this journal in the first half of 2025).