

Special Issue

Swarm Robotics for Agricultural Applications

Message from the Guest Editor

The focus of this Special Issue of *AgriEngineering* is the application of swarm robotics to agriculture. We seek studies with experimental results involving agricultural robots designed to operate autonomously, in parallel, and scalably. Sensors, software, end-effectors, and other payloads particularly suited for use with such robots will also be considered. By collecting several recent developments between covers, this issue seeks to achieve the critical mass needed to inspire a revolution in *practical* agricultural swarm robotics. For further reading, please visit the [Special Issue website](#).

Guest Editor

Prof. Dr. Matt Haberland

BioResource and Agricultural Engineering Department, California Polytechnic State University, San Luis Obispo, CA 93407, USA

Deadline for manuscript submissions

closed (1 November 2021)



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AgriEngineering
Editorial Office
MDPI, Grosspeteranlage 5
4052 Basel, Switzerland
Tel: +41 61 683 77 34
agriengineering@mdpi.com

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About the Journal

Message from the Editor-in-Chief

AgriEngineering (ISSN 2624-7402) is an international open access, open-source, and cross-disciplinary scientific journal on the engineering science of agricultural and horticultural production. Our aim is to encourage scientists to publish their experimental and theoretical research, along with the full set of schematics, source-code, and mechanical design models leading to accelerated and rapid dissemination of leading-edge technologies emerging in agricultural, environmental, and agronomic engineering. *AgriEngineering* publishes articles, technical notes, reviews, commentaries, and case/field reports, as well as Special Issues on particular subjects.

Editor-in-Chief

Prof. Dr. Francesco Marinello

Department of Land, Environment, Agriculture and Forestry, University of Padova, 35020 Legnaro, Padova, Italy

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manuscripts are peer-reviewed and a first decision is provided to authors approximately 22 days after submission; acceptance to publication is undertaken in 6.3 days (median values for papers published in this journal in the second half of 2025).