# **Special Issue**

# Motion Planning and Control of Robot Systems

# Message from the Guest Editors

As various types of robots begin to be applied in industry and human life, research on systematic approaches for robot motion planning and control has been in progress in recent years. This Special Issue is devoted to coverage of motion planning and control for robotic systems in different applications. Original papers and survey papers are welcome. Topics of interest for this collection include but are not limited to:

- motion planning
- control algorithm
- force/torque control
- robust control
- manipulators
- mobile robotics
- multirobot systems

## **Guest Editors**

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## Deadline for manuscript submissions

closed (31 December 2023)



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# About the Journal

# Message from the Editorial Board

We are just entering the Next Wave of Technology (NWT) where actuators will play the same role as the computer chip did for computers/social media approximately four decades ago. Just in the U.S., production of \$1 trillion year of electromechanical systems (vehicles, orthotics, manufacturing cells, freight trains, aircraft, etc.) will be impacted by the NWT, all driven by actuators. Five key trends can be found for the future perspectives: "Performance to Reliability", "Hard to Soft", "Macro to Nano", "Homo to Hetero" and "Single to Multi functional". We invite papers that primarily impact these economic sectors; those illustrating basic scientific principles are also welcome.

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